

Graph matching from a statistical perspective

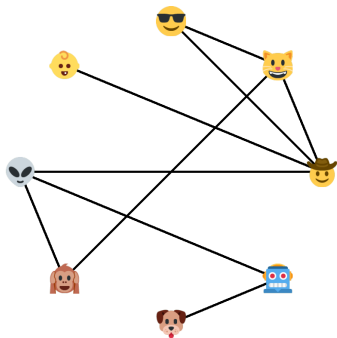
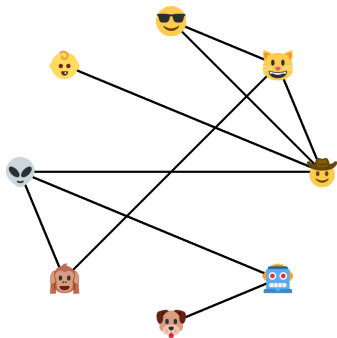
Jesús Arroyo

October 4th, 2023

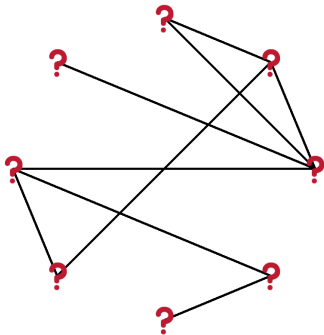
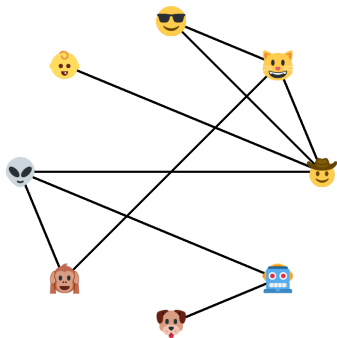
Texas A&M University

Stat Café

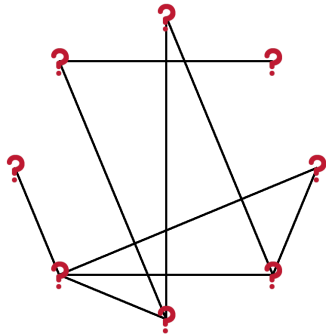
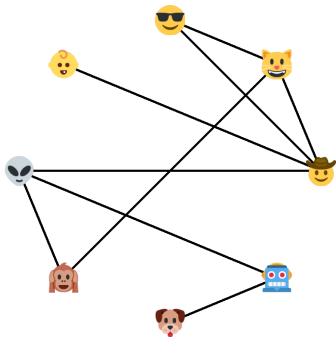
Graph matching



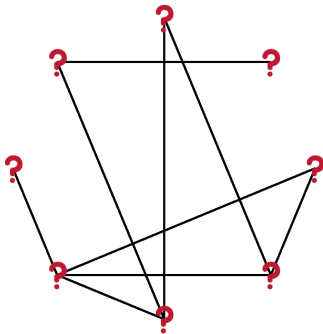
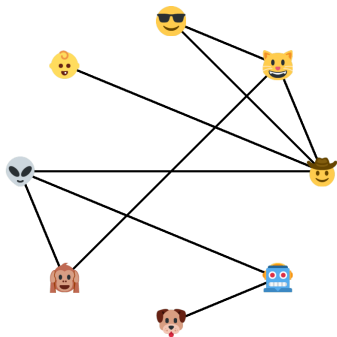
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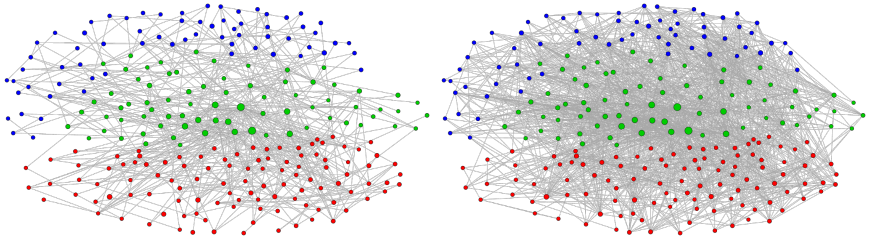


Exact graph matching = graph isomorphism problem

Graph matching

In real datasets, graph matching is usually **inexact**:

- Aligning biological networks
- Image/video/text processing
- De-anonymizing social networks
- Record linkage

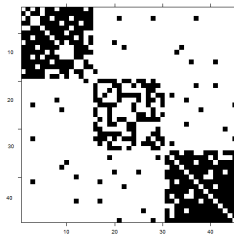
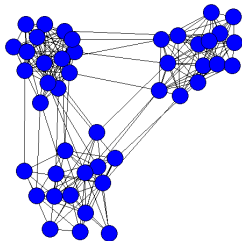


The *C. elegans* chemical and electrical connectomes (Chen et al. 2016, *Worm*)

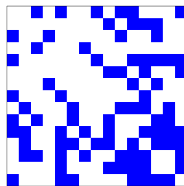
Notation:

- Consider two *simple* graphs with n vertices each.
- Graphs are represented by their adjacency matrices $A, B \in \{0, 1\}^{n \times n}$.

Goal: align the rows and columns of A and B



Graph matching problem

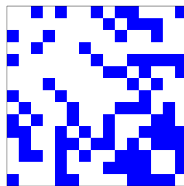


Two main approaches:

- **Algorithmic**: optimization, search strategies, spectral methods, etc. (Conte et al., 2004; Foggia et al., 2014). E.g.: *quadratic assignment problem* (QAP):

$$\operatorname{argmin}_{\text{permutation } P} \sum_{i \neq j} (A_{ij} - (PBP^T)_{ij})^2 = \operatorname{argmax}_{\text{permutation } P} \langle A, PBP^T \rangle.$$

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- **Random graph models**: pair of graphs generated from some distribution. E.g. correlated Erdős-Rényi graph model (Lyzinski et al., 2014)

$$A_{ij} \sim \text{Ber}(p), \quad B_{ij} \sim \text{Ber}(p),$$

$$\text{Corr}(A_{ij}, B_{ij}) = \rho \geq 0.$$

This talk

Overview:

- Random graph models for the graph matching problem
- Matching via maximum likelihood estimation
- Theory: when is MLE consistent for graph matching?
- Computational aspects: non-convex relaxations
- Illustrations on simulated and real networks

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- Matching via maximum likelihood estimation
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Problems considered:

- Unipartite to unipartite graph matching
- Bipartite to unipartite graph matching
- Some future directions

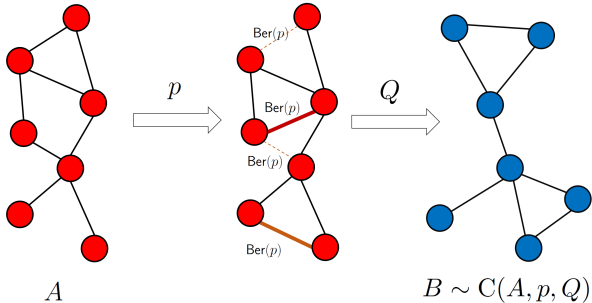
Graph matching in errorfully observed networks

Graph matching between bipartite and unipartite networks

Corrupting channel model

Model: B is an edge and vertex-label corrupted version of A

1. Flip edges and non-edges of A with probability p .
2. Shuffle vertices with permutation Q .



Maximum likelihood estimation and graph matching

- Maximum likelihood estimator:

$$(\hat{p}_{\text{MLE}}, \hat{Q}_{\text{MLE}}) := \operatorname{argmax}_{p, Q} \sum_{u > v} \log \mathbb{P}_p (A_{uv} = (QBQ^T)_{uv}).$$

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$$\hat{Q}_{\text{MLE}} = \operatorname{argmin}_{Q \in \Pi_n} \|A - QBQ^T\|_F^2.$$

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- Extensions to non-uniform corrupting probabilities: the equivalence between MLE and QAP also holds.

When is the MLE correct?

- Difficulty lies on how different A and QAQ^T are, for any $Q \neq I$:

$$\|A - QAQ^T\|_F^2 = \sum_{i \neq j} (A_{ij} - A_{\sigma(i), \sigma(j)})^2.$$

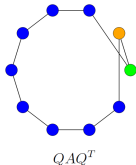
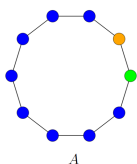
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Examples:

- $k = 2$
- $\|A - QAQ^T\|_F^2 = 4.$



When is the MLE correct?

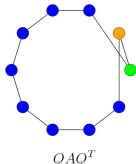
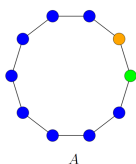
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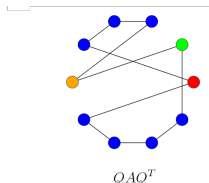
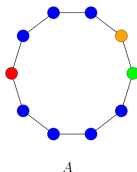
- $k = 2$

- $\|A - QAQ^T\|_F^2 = 4.$



- $k = 3$

- $\|A - QAQ^T\|_F^2 = 10.$



$\Pi_{n,k}$ permutations that shuffle exactly k vertices.

Consistency of the MLE

Sequence of networks $\{A_n\}$ and parameters $\{p_n, Q_n\}$

Theorem (A., Sussman, Priebe, Lyzinski, 2021)

- \hat{Q}_{MLE} is **consistent** (*correct matching in the limit*) if

$$\min_{Q \in \Pi_{n,k}} \|A_n - QA_nQ^T\|_F^2 \geq \frac{6k \log n}{(1/2 - p_n)^2}, \quad \forall k \geq 2.$$

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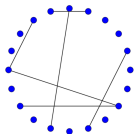
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- \hat{Q}_{MLE} is **not consistent** if there exists $m = \Omega(n)$ disjoint permutations Q_1, \dots, Q_m

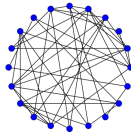
$$\max_{i \in [m]} \|A_n - Q_i A_n Q_i^T\|_F^2 = o\left(\frac{\log n}{(1/2 - p_n)^2}\right).$$

Erdős-Rényi graph model

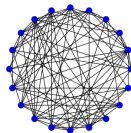
$$A_n \sim G(n, \alpha_n)$$



$\alpha = 0.05$



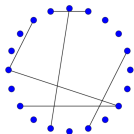
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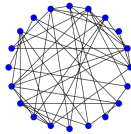
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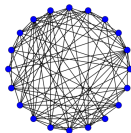
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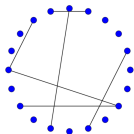
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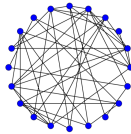
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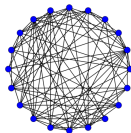
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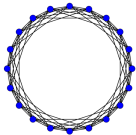
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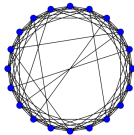
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Small-world networks

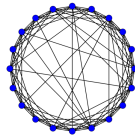
Newman-Watts model: $A_n \sim \text{NW}(n, d_n, \beta_n)$,



$d = 4,$
 $\beta = 0$



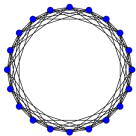
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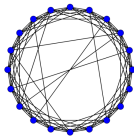
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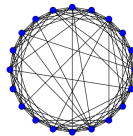
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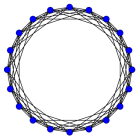
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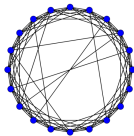
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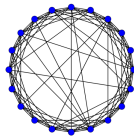
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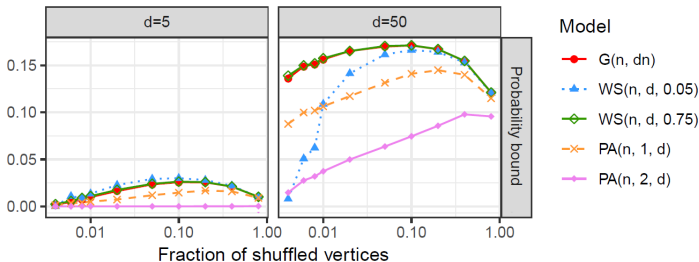
- \hat{Q}_{MLE} is **consistent** if $d_n = o(\beta_n^2 n)$ and

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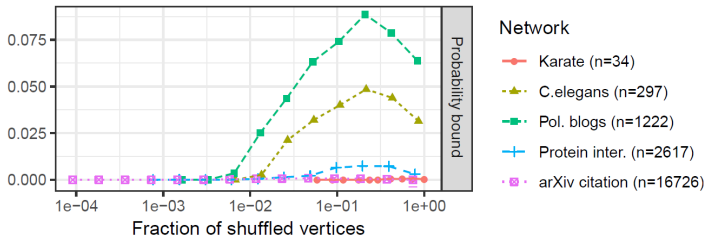
Matchability on random graphs

Measure matching feasibility: Upper bound for the noise probability tolerated by a graph based on the theory

- Erdős-Rényi $G(n, dn)$
- Watts-Strogatz small-world $WS(n, d, \beta)$
- Preferential attachment $PA(n, \gamma, d)$



Matchability on real networks

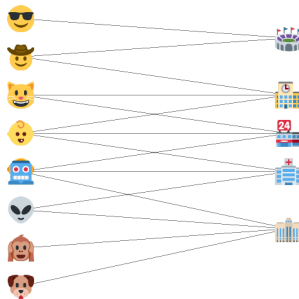
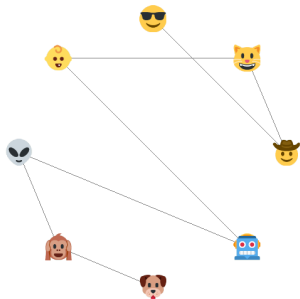


Graph matching in errorfully observed networks

Graph matching between bipartite and unipartite networks

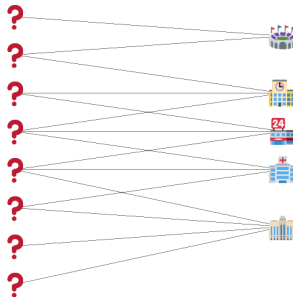
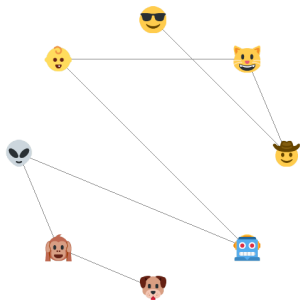
Data integration

- Data are often collected from different sources or modalities
- In particular, now consider **unipartite** and **bipartite** graphs



Data integration

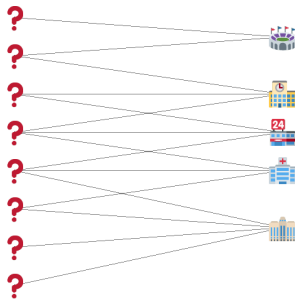
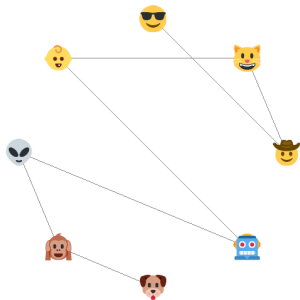
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- In particular, now consider **unipartite** graphs and **bipartite** data



Graph matching

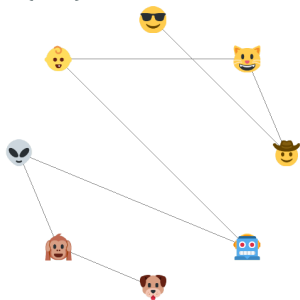
Goal: graph matching between **bipartite** and **unipartite** networks

- *Methodology:* joint model based on undirected graphical models
- *Graph matching:* use MLE to find unshuffling permutation
- *Optimization:* non-convex relaxation via graphical lasso and fast QAP

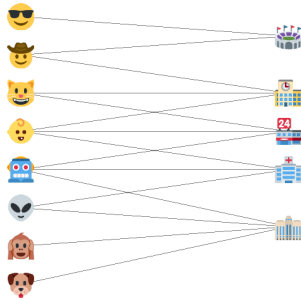


Graph matching formulation

$A \in \{0, 1\}^{n \times n}$ adjacency matrix,

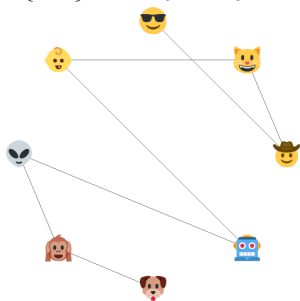


$B \in \mathbb{R}^{n \times m}$ incidence or data matrix

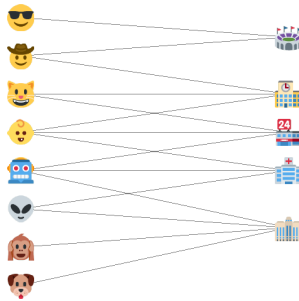


Graph matching formulation

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Undirected graphical model for B conditioned on A

- **Local Markov property:** edges of vertex i are conditionally independent to other edges given the values of the neighbors of i . If X is a column of B

$$X_i \perp X_{[n] \setminus \mathcal{N}_i(A) \cup \{i\}} \mid X_{\mathcal{N}_i(A)}, \quad \forall i \in [n].$$

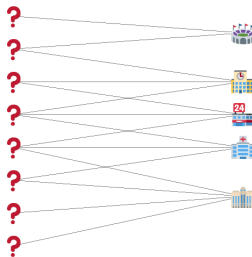
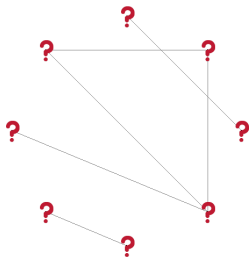
Graph matching formulation

- Generalized linear model distributions (Yang et al., 2012) to make the problem tractable.

$$f_X(x_i \mid x_{[n] \setminus \{i\}}) \propto \exp\left(\beta_i x_i + \sum_{j \in \mathcal{N}_i(W)} \Theta_{ij} x_i x_j - 2\Theta_{ii} C(x_i)\right),$$

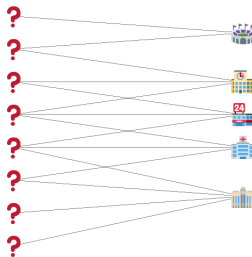
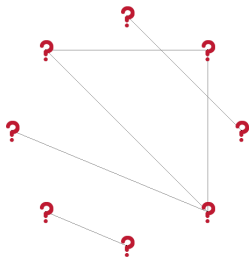
- $\Theta_{ij} = 0$ if $A_{ij} = 0$ (local Markov property)
- Special cases: Ising model, Gaussian graphical model

Bipartite-to-unipartite graph matching formulation



- **Graph matching:** we observe $A' = P^* A (P^*)^T$ for a permutation P^* .

Bipartite-to-unipartite graph matching formulation

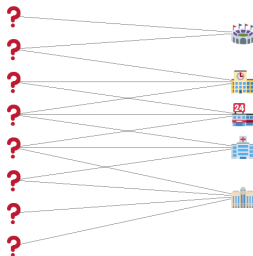
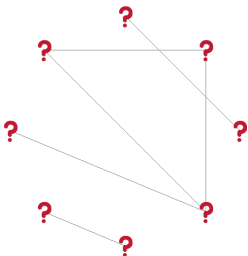


- **Graph matching:** we observe $A' = P^* A (P^*)^T$ for a permutation P^* .
- Solve restricted *maximum likelihood estimation*:

$$(\hat{P}, \hat{\Theta}) = \underset{P, \Theta}{\operatorname{argmax}} \quad \ell(\Theta)$$

subject to $\Theta_{ij}(1 - (P^T A' P)_{ij}) = 0, \quad i \neq j,$
 P is a permutation matrix,

Exact graph matching recovery



Theorem (A., Priebe, Lyzinski, 2021)

Suppose that $\Theta_{ij}^* \neq 0$ if $((P^*)^\top AP^*)_{ij} = 1, i \neq j$.

Under **regularity conditions**, if

$$\underbrace{\min_{P \neq I} \|A - P^\top AP\|_F^2}_{\substack{\text{Graph matching difficulty} \\ (\text{Lyzinski et al., 2016; A. et al., 2021})}} \geq \underbrace{C \frac{(\|A\|_F^2 + n) \log n}{m}}_{\substack{\text{Graphical model estimation error} \\ (\text{Rothman et al., 2008})}},$$

then $\hat{P} = P^*$ with high probability.

Graph matching algorithm

- Maximum likelihood estimation is NP-hard!

Graph matching algorithm

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- Strategy to find an approximate solution:
 1. Relax permutation Q to a doubly stochastic matrix D
 2. Write the problem in a Lagrangian formulation
 3. Alternating optimization for D and Θ .

Graph matching algorithm

- Maximum likelihood estimation is NP-hard!
- Strategy to find an approximate solution:
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 3. Alternating optimization for D and Θ .
- All steps have efficient solutions!
- For Gaussian graphical models, the new optimization problem is

$$\operatorname{argmax}_{D, \Theta} \left\{ \log \det \Theta - \operatorname{trace}(\hat{\Sigma} \Theta) - \lambda \sum_{i \neq j} |(1 - (D^T A D)_{ij}) \Theta_{ij}| \right\}$$

1. Optimization for Θ : weighted graphical lasso (Friedman et al. 2008)
2. Optimization for D : quadratic assignment problem (Vogelstein et al., 2014, Lyzinski et al., 2016)

Matching via inverse covariance estimation

Algorithm 1 Unipartite to bipartite matching via penalized inverse covariance estimation

Input: Adjacency matrix A , incidence matrix B .

```
for each  $\lambda \in \{\lambda_s\}_{s=1}^{S^*}$  do  
  Initialize  $\hat{D}^{(1,\lambda)} = \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^\top$ .  
  for  $t = 1, \dots, T^*$ , or until convergence do  
    Update  $\hat{\Theta}^{(t,\lambda)}$  by solving (3.6).  
    Update  $\hat{D}^{(t+1,\lambda)}$  by solving (3.7).  
    Set  $\hat{P}^{(t+1,\lambda)}$  as the projection of  $\hat{D}^{(t,\lambda)}$  into  $\Pi_n$ .  
  end for
```

end for

Choose the permutation with the largest value of $\hat{\ell}(\hat{\Theta}_P)$ among the permutations $P \in \{P^{(t,\lambda_s)}, s \in [S^*], t \in [T^*]\}$.

Output: Permutation \hat{P} , inverse covariance estimate $\hat{\Theta}_{\hat{P}}$.

Matching via penalized pseudolikelihood

- Use pseudolikelihood when likelihood is intractable (e.g., Ising model).

Algorithm 2 Unipartite to bipartite matching via penalized pseudolikelihood

Input: Adjacency matrix A , incidence matrix B .

for each $\lambda \in \{\lambda_s\}_{s=1}^{S^*}$ **do**

Initialize $\hat{D}^{(1,\lambda)} = \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^\top$.

for $t = 1, \dots, T^*$, or until convergence **do**

for $j = 1, \dots, n$ **do**

Update $(\hat{\Theta}_j^{(t,\lambda)}, \hat{\beta}_j^{(t,\lambda)})$ by solving (3.9).

end for

Update $\hat{D}^{(t+1,\lambda)}$ by solving (3.7).

Set $\hat{P}^{(t+1,\lambda)}$ as the projection of $\hat{D}^{(t,\lambda)}$ into Π_n .

end for

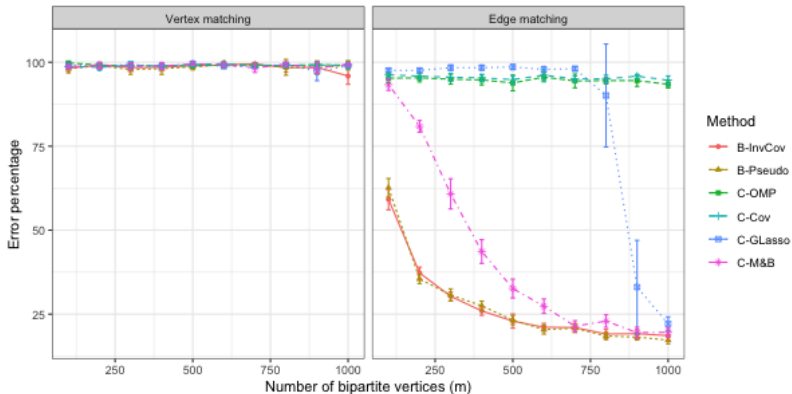
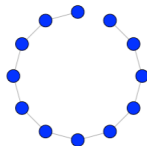
end for

Choose the permutation with the largest value of $\tilde{\ell}(\hat{\Theta}_P)$ among $P \in \{P^{(t,\lambda_s)}, s \in [S^*], t \in [T^*]\}$.

Output: Permutation \hat{P} , estimated parameters $\hat{\Theta}_{\hat{P}}$ and $\hat{\beta}_{\hat{P}}$.

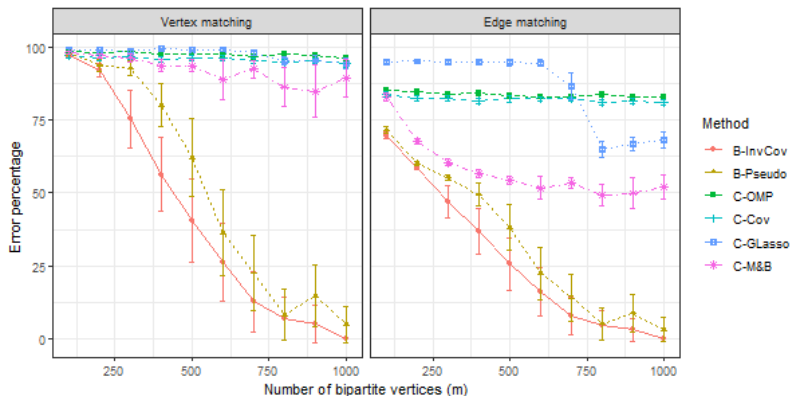
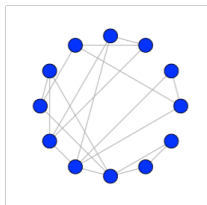
Simulation experiment 1

- A (unipartite) is a **chain graph**, B follows Ising model
- Graphical model estimation: **easy**
- Graph matching: **hard**

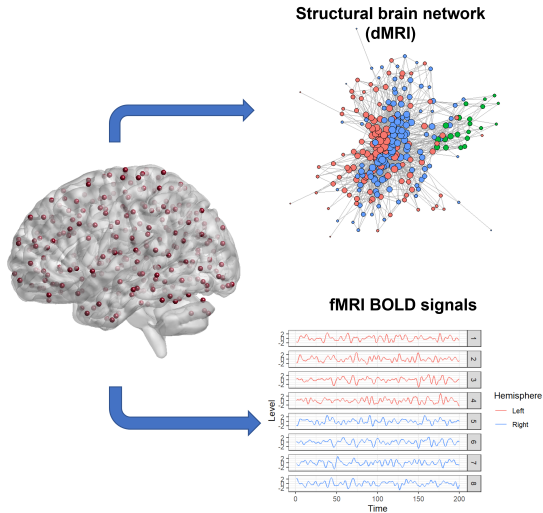


Simulation experiment 2

- A (unipartite) is an **Erdős-Rényi** graph
- Graphical model estimation: **hard**
- Graph matching: **easy**

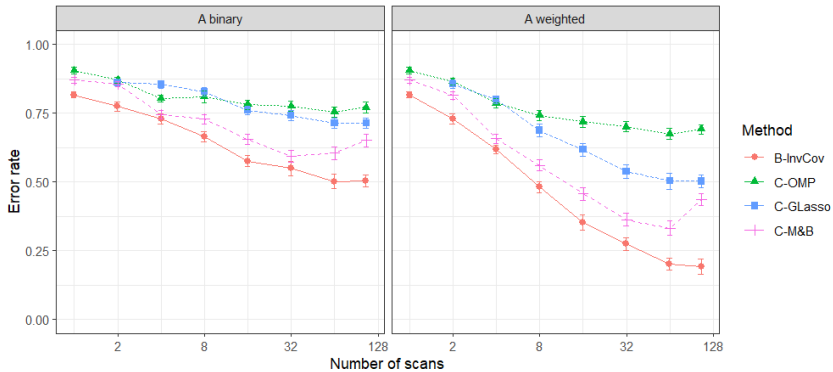


Magnetic resonance imaging (MRI) data



Structural and functional MRI data (Zuo et al, 2014).

MRI data

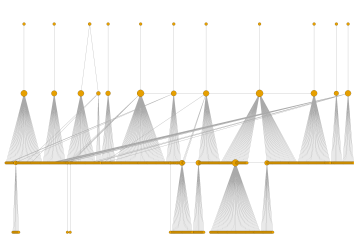


Concluding remarks

- Integrating multiple data sources often requires to match the units
- Statistical approaches based on random graph models for matching
- Combining information may improve performance
- Graph matching with other data structures? Networks with attributes, multilayer or time-varying graphs.
- Statistical inference for multiple networks? (after matching)

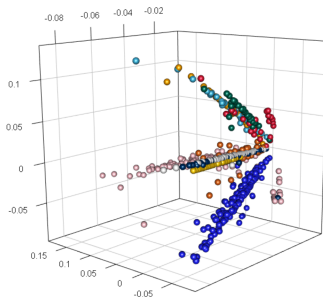
Future directions

- Work in progress: academic and collaboration networks (data collected by Xingyu Liu and Yufan Li)
- Integration of different network data sources:
 - Efficient graph matching methods
 - Joint statistical models for heterogeneous modalities
 - Statistical inference problems



New course for Spring 2024!

- Special Topics in Network Data Analysis (STAT 689)
- Tue - Thu 11:10 - 12:25 (3 credits)
- Supported by TAMIDS Course Development Program



Thank you!

Questions?

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Main references:

- Arroyo, J., Sussman, D.L., Priebe, C.E. and Lyzinski, V. (2021) "Maximum Likelihood Estimation and Graph Matching in Errorfully Observed Networks", *Journal of Computational and Graphical Statistics* 30:4.
- Arroyo, J., Priebe, C.E. and Lyzinski, V. (2021) "Graph matching between bipartite and unipartite networks: to collapse, or not to collapse, that is the question", *IEEE Trans. on Network Science and Engineering*